Embedding of low-dimensional manifolds in RNN

Part of Lecture 4 by R. Monasson





Space of neural configurations x_i (N-dimensional)

Attractors in Recurrent Neural Nets

Set of neural configurations:

$${x_i^{\mu}}, i = 1...N, \mu = 1...P$$

Set of fixed point conditions:

$$x_i^{\mu} = sign\left(\sum_j J_{ij} x_j^{\mu}\right), \forall i, \mu$$

Equivalent to classification of P inputs/ouputs with N perceptrons (rows of J matrix)

Possible as long as $\alpha = \frac{P}{N} < 2$ if neural configurations are uncorrelated NB: different from $y^{\mu} = sign\left(\sum_{j} J_{j} x_{j}^{\mu}\right), \forall \mu$

Place cells and place fields

Place cells in the hippocampus regions CA1 and CA3 present spatially localized firing fields



- Persists in the absence of input stimuli (dark)
- Place fields are retrieved when the animal is placed in the same environment after days

Multiple CANN

• Different representations of the same environment can be memorized and recalled upon contextual change on very short time scales

[Kelemen, Fenton, PLoS Biology 2010]



• Different environments need to be memorized in the same network; apparently random remapping of place fields across environment

[Alme et al. "Place cells in the hippocampus: Eleven maps for eleven rooms.", PNAS 2014]

Multiple Continuous Attractor Neural Networks





Space of neural configurations x_i (N-dimensional)

Multiple Continuous Attractor Neural Networks



L manifolds

p points

Trade-off between quantity (capacity) and quality (accuracy over « position » along attractor)

Space of neural configurations x_i (N-dimensional)

Formulation of the learning problem: data

- N neurons (i=1...N), L manifolds (μ=1...L) of dimension D
- Each neuron i has a place field in manifold μ centered in $\vec{r}_{i}^{(\mu)}$
- panchoring points $\vec{r}^{(m)}$ (m=1...p) per manifold: controls accuracy ε of

L x p data configurations
$$x_i^{(\mu,m)} = \Phi\left(\left|\vec{r}^{(m)} - \vec{r}_i^{(\mu)}\right|\right) = 0,1$$

Example:

N=5, L=2, D=2, p=3

(periodic boundary conditions)



 $\varepsilon \approx p^{-1/D}$

representation

Formulation of the learning problem: optimal couplings

• RNN dynamics:

$$x_{i}(t+1) = f\left(\sum_{j} J_{ij} x_{j}(t)\right) \text{ with } f(u) = 0 \text{ if } u < 0$$

1 if $u > 0$

• Minimal conditions: data configurations should be fixed points

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• Optimal set of couplings **J** of RNN maximizes

$$\kappa(J) = \min_{\{i=1...N, \mu=1...L, m=1...p\}} \left[(2x_i^{(\mu,m)} - 1) \sum_j J_{ij} x_j^{(\mu,m)} \right]$$

Similar to maximal hard margin: can be done with standard SVM techniques



Auto-associative mapping: unsupervised learning of the manifolds

Results: bump spans manifold



Here: noisy version of the dynamics of RNN



Results: transitions from manifold to manifold



N=1000 L=2

Here: noisy version of the dynamics of RNN

p=150

Optimal capacity



Optimal capacity



Optimal capacity: asymptotic theory



Large-p behavior:

$$\alpha_c(p) \approx \frac{A(D, \Phi)}{(\log p)^D}$$

Very slow decrease of capacity with spatial resolution $\varepsilon \approx p^{-1/D}$, e.g.

$$\varepsilon \rightarrow \varepsilon^2, \, \alpha_c \rightarrow \alpha_c \,/\, 2^D$$

[Battista & RM, Phys Rev Lett 2020]

Connection with Multi-space Euclidean Random Matrices

The result on the previous slide relies on the spectral properties of MERM:



[Battista & RM, Phys Rev E 2020]

$$C_{ij}\left(\left\{\vec{r}_{i}^{(\mu)}\right\}\right) = \frac{1}{L}\sum_{\mu=1}^{L}\gamma\left(\left|\vec{r}_{i}^{(\mu)} - \vec{r}_{j}^{(\mu)}\right|\right)$$

- Simple for L=1: high-density regime of ERM (eigenmodes ~ Fourier plane waves)
- Non trivial due to incoherent superimpositions of maps
- Self-consistent equation for the spectrum $hoig(\lambda;lphaig)$ (in fact, its resolvent) can be established with standard random matrix theory techniques